

**Description**

The A50A200I PWM servo drive is designed to drive brushed type DC motors at a high switching frequency. A single red/green LED indicates operating status. The drive is fully protected against over-voltage, under-voltage, over-current, over-heating and short-circuits across motor, ground and power leads. Furthermore, the drive can interface with digital controllers or be used stand-alone, and requires only a single unregulated DC power supply. Loop gain, current limit, input gain and offset can be adjusted using 14-turn potentiometers. The offset adjusting potentiometer can also be used as an on-board input signal for testing purposes. This drive can use a tachometer for velocity control.

See Part Numbering Information on last page of datasheet for additional ordering options. The hardware installation manual for the AxCent™ drive family is available for download at [www.a-m-c.com](http://www.a-m-c.com).

**Power Range**

Peak Current	50 A
Continuous Current	25 A
Supply Voltage	40 - 175 VDC



**Features**

- ▲ Four Quadrant Regenerative Operation
- ▲ DIP Switch Selectable Modes
- ▲ DIP Switch Configurable Loop Tuning
- ▲ DIP Switch Configurable Current Scaling
- ▲ DIP Switch Configurable Tachometer Scaling
- ▲ Selectable Inhibit Logic
- ▲ Selectable Command Input
- ▲ High Switching Frequency
- ▲ Digital Fault Output Monitor
- ▲ On-Board Test Potentiometer
- ▲ Offset Adjustment Potentiometer
- ▲ Adjustable Input Gain
- ▲ Adjustable Current Limits
- ▲ Current Monitor Output
- ▲ Drive Status LED
- ▲ Directional Inhibit Inputs for Limit Switches

**MODES OF OPERATION**

- Current
- Duty Cycle
- Tachometer Velocity
- Voltage
- IR Compensation

**COMMAND SOURCE**

- ±10 V Analog
- PWM and Direction

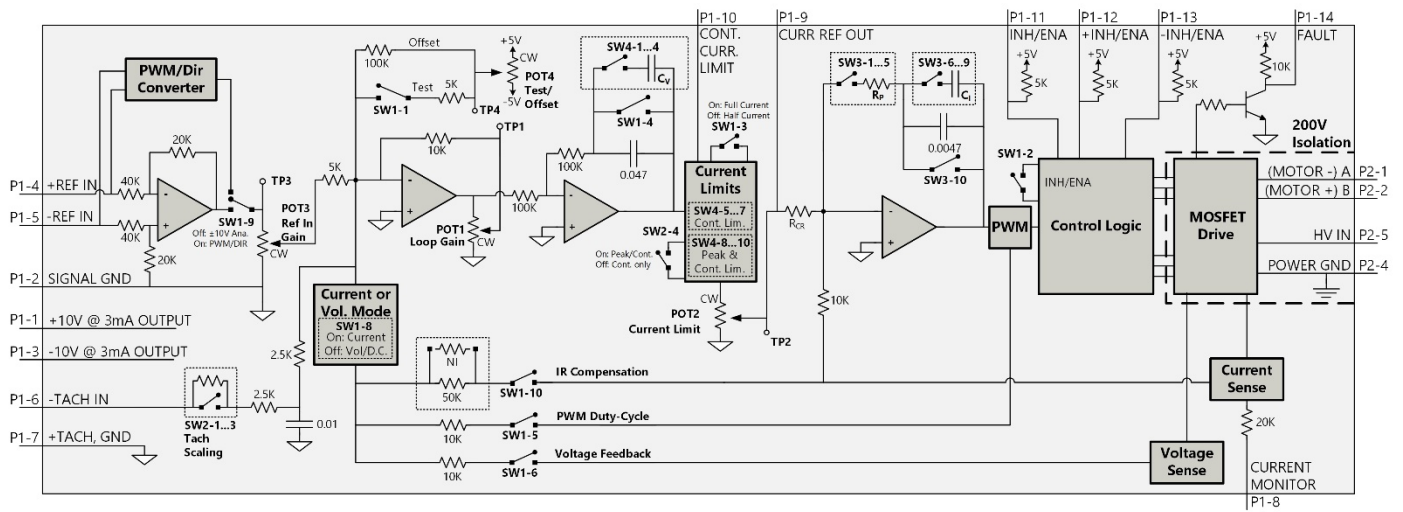
**FEEDBACK SUPPORTED**

- Tachometer (±60VDC)

**COMPLIANCES & AGENCY APPROVALS**

- UL
- cUL
- CE Class A (LVD)
- CE Class A (EMC)
- RoHS II

**BLOCK DIAGRAM AND AGENCY APPROVALS**



Mode Selection Table						
Mode	SW1-4	SW1-5	SW1-6	SW1-8	SW1-10	Tachometer
Current Mode	ON	OFF	OFF	ON	OFF	Not Connected
Duty Cycle Mode	OFF	ON	ON	OFF	OFF	Not Connected
Voltage Mode	OFF	OFF	ON	OFF	OFF	Not Connected
IR Compensation Mode	OFF	OFF	ON	OFF	ON	Not Connected
Tachometer Velocity Mode	OFF	OFF	OFF	OFF	OFF	Connected

LED Behavior	
Color	Function
Green	Normal Operation
Red	Fault Condition

Default mode is Current Mode, with maximum current settings.  
Recommended potentiometer setting for Current Mode is:  
Pot 1 = Full CCW, Pot 2 = Full CW, Pot 3 = Full CW.

**Information on Approvals and Compliances**



US and Canadian safety compliance with UL 61800-5-1, the industrial standard for adjustable speed electrical power drive systems. UL registered under file number E140173. Note that machine components compliant with UL are considered UL registered as opposed to UL listed as would be the case for commercial products.



Compliant with European EMC Directive 2004/108/EC on Electromagnetic Compatibility (specifically EN 61000-6-4:2007/A1:2011 for Emissions, Class A and EN 61000-6-2:2005 for Immunity, Performance Criteria A). LVD requirements of Directive 2006/95/EC (specifically, EN 60204-1:2006/A1:2009, a Low Voltage Directive to protect users from electrical shock).



The RoHS II Directive 2011/65/EU restricts the use of certain substances including lead, mercury, cadmium, hexavalent chromium and halogenated flame retardants PBB and PBDE in electronic equipment.

**SPECIFICATIONS**

<b>Power Specifications</b>		
Description	Units	Value
DC Supply Voltage Range	VDC	40 - 175
DC Bus Over Voltage Limit	VDC	194
DC Bus Under Voltage Limit	VDC	32
Maximum Peak Output Current <sup>1</sup>	A	50
Maximum Continuous Output Current	A	25
Maximum Continuous Output Power at Continuous Current	W	4156
Maximum Power Dissipation at Continuous Current	W	219
Minimum Load Inductance (Line-To-Line) <sup>2</sup>	μH	250 (@ 100 VDC supply or greater); 200 (@ less than 100 VDC supply)
Internal Bus Capacitance	μF	75
Low Voltage Supply Outputs	-	±10 VDC (3 mA)
Switching Frequency	kHz	24
<b>Control Specifications</b>		
Description	Units	Value
Command Sources	-	±10 V Analog, PWM and Direction
Feedback Supported	-	Tachometer (±60 VDC)
Commutation Methods	-	Trapezoidal
Modes of Operation	-	Current, Duty Cycle, Tachometer Velocity, Voltage, IR Compensation
Motors Supported	-	Single Phase (Brushed, Voice Coil, Inductive Load)
Hardware Protection	-	Over-Current, Over-Temperature, Over-Voltage, Under-Voltage, Short-Circuit (Phase-Phase & Phase-Ground)
Primary I/O Logic Level	-	5V TTL
<b>Mechanical Specifications</b>		
Description	Units	Value
Agency Approvals	-	CE Class A (EMC), CE Class A (LVD), cUL, RoHS II, UL
Size (H x W x D)	mm (in)	186.7 x 108.8 x 26.9 (7.35 x 4.28 x 1.10)
Weight	g (oz)	498.95 (17.6)
Heatsink (Base) Temperature Range <sup>3</sup>	°C (°F)	0 - 65 (32 - 149)
Storage Temperature Range	°C (°F)	-40 - 85 (-40 - 185)
Form Factor	-	Panel Mount
P1 Connector	-	16-pin, 2.54 mm spaced, friction lock header
P2 Connector	-	5-port, 11.10 mm spaced, screw terminal

**Notes**

1. Maximum duration of peak current is ~2 seconds. Peak RMS value must not exceed continuous current rating of the drive.
2. Lower inductance is acceptable for bus voltages well below maximum. Use external inductance to meet requirements.
3. Additional cooling and/or heatsink may be required to achieve rated performance.

**PIN FUNCTIONS**

P1 - Signal Connector				
Pin	Name	Description / Notes	I/O	
1	+10V 3mA OUT	±10 V @ 3 mA low power supply for customer use. Short circuit protected. Reference ground common with signal ground.	O	
2	SIGNAL GND		GND	
3	-10V 3mA OUT		O	
4	+REF IN or DIR	Differential Reference Input (±10 V Operating Range, ±15 V Maximum Input) or PWM and Direction input (10kHz – 30kHz input range, 0-100% duty cycle). SW1-9 selects the command input type. OFF is ±10V analog, ON is PWM and Direction.	I	
5	-REF IN or PWM		I	
6	-TACH IN	Negative Tachometer Input (Maximum ±60 V). Use signal ground for positive input.	I	
7	+TACH / GND	Positive Tachometer Input and Signal Ground	GND	
8	CURR MONITOR OUT	Current Monitor. Analog output signal proportional to the actual current output. Scaling is 8.12 A/V by default but may be reduced to half this value by setting DIP switch SW1-3 to OFF (see Hardware Settings section below). Measure relative to signal ground.	O	
9	CURRENT REF OUT	Measures the command signal to the internal current-loop. This pin has a maximum output of ±7.25 V when the drive outputs maximum peak current. Measure relative to signal ground.	O	
10	CONT CURRENT LIMIT	Can be used to reduce the factory-preset maximum continuous current limit without affecting the peak current limit by attaching an external current limiting resistor between this pin and signal ground. See pin details below for resistor values.	I	
11	INHIBIT / ENABLE	TTL level (+5 V) inhibit/enable input. Pull to ground to inhibit drive (SW1-2 ON). Pull to ground to enable drive (SW1-2 OFF). Inhibit turns off all power devices.	I	
12	+INHIBIT / ENABLE	Positive Direction Inhibit (Does Not Cause A Fault Condition). Pull to ground to inhibit positive direction (SW1-2 ON). Pull to ground to enable positive direction (SW1-2 OFF).	I	
13	-INHIBIT / ENABLE	Negative Direction Inhibit (Does Not Cause A Fault Condition). Pull to ground to inhibit negative direction (SW1-2 ON). Pull to ground to enable negative direction (SW1-2 OFF).	I	
14	FAULT OUT	TTL level (+5 V) output becomes high when power devices are disabled due to at least one of the following conditions: inhibit, output short circuit, over voltage, under voltage, over temperature, power-up reset.	O	
15	RESERVED	Reserved.	-	
16	RESERVED		-	

P2 - Power Connector				
Pin	Name	Description / Notes	I/O	
1	A	Negative Motor Output	O	
2	B	Positive Motor Output	O	
3	C	Not Connected	O	
4	POWER GND	Power Ground	PGND	
5	HIGH VOLTAGE	DC Power Input	I	

**Pin Details**

*CONT CURRENT LIMIT (P1-10)*

This pin can be used to reduce the continuous current limit without affecting the peak current limit by connecting an external current limiting resistor between this pin and signal ground. See table below.

Current Limit Resistor	18 kΩ	6.5 kΩ	3.4 kΩ	2.5 kΩ	1.8 kΩ	1 kΩ	800 Ω	300 Ω	0 kΩ
Continuous Current Limit	90%	80%	70%	65%	60%	50%	45%	40%	30%

Note: These values are secondary to the continuous/peak ratio set by the DIP switches.

**HARDWARE SETTINGS**

**Configuration Switch Functions**

SW1	Description	Setting	
		On	Off
1	Test/Offset. Switches the function of the Test/Offset pot between an on-board command input for testing or a command offset adjustment. OFF by default.	Test	Offset
2	Inhibit logic. Sets the logic level of inhibit pins.	Drive Inhibit is active low	Drive Inhibit is active high
3	Current scaling. When OFF, increases sensitivity of current sense thus reducing both peak and continuous current limit by 50%. The scaling of the current monitor output signal becomes ½ its ordinary value when this switch is OFF.	Full-current	Half-current
4	Outer loop integration. Activates or deactivates integration. ON, by default, for current mode and OFF for other modes.	Inactive	Active
5	Mode selection. See mode selection table below.	-	-
6		-	-
7		-	-
8	Mode selection. See mode selection table below.	-	-
9	±10V Analog or PWM and Direction command input selection. Changes pins 4 and 5 on P1 between +REF/-REF and DIR/PWM.	PWM and Direction	±10V Analog
10	IR compensation. Activates or deactivates IR feedback. ON for IR compensation mode and OFF for other modes.	On	Off

*Mode Selection Table*

	SW1-4	SW1-5	SW1-6	SW1-8	SW1-10	Tachometer
CURRENT	ON	OFF	OFF	ON	OFF	Not Connected
DUTY CYCLE	OFF	ON	ON	OFF	OFF	Not Connected
VOLTAGE	OFF	OFF	ON	OFF	OFF	Not Connected
TACHOMETER VELOCITY	OFF	OFF	OFF	OFF	OFF	Connected
IR COMPENSATION	OFF	OFF	ON	OFF	ON	Not Connected

*IR Compensation Mode*

For applications that will use IR Compensation mode, a resistor can be added to an SMT location on the PCB<sup>†</sup> (in parallel to existing 50kΩ resistor already on the PCB) to scale the IR Compensation feedback. The combination of the appropriate resistance value and correct DIP switch settings will configure the amplifier for IR Compensation mode. While in IR Compensation mode, the drive will adjust the duty cycle to compensate for changes in the output current. Contact the factory for assistance and instructions before modifying the drive.

**\*Note: Damage done to the drive while performing this modification will void the warranty.**

**(Note: Drive cover must be removed to access SW2)**

SW2	Description	Setting	
		On	Off
1	Tachometer Input Voltage Scaling. Adjusts the maximum range of the tachometer input.	Max tachometer input values from 5V to 61V. See Maximum Tachometer Input Voltage Table below.	
2			
3			
4	Configures the drive to output either peak and continuous current values, or continuous current only.	Peak and Continuous Current	Continuous Current Only

*Maximum Tachometer Input Voltage Table*

Default switch settings are shaded.

Switch	Maximum Tachometer Input Voltage (±VDC)							
	61	53	45	37	29	21	13	5
SW2-1	OFF	ON	OFF	ON	OFF	ON	OFF	ON
SW2-2	OFF	OFF	ON	ON	OFF	OFF	ON	ON
SW2-3	OFF	OFF	OFF	OFF	ON	ON	ON	ON

**(Note: Drive cover must be removed to access SW4)**

SW4	Description	Setting
1	Advanced Tuning (Velocity Loop Integrator Capacitance)	See SW4 table in Loop Tuning Switch Functions section for switch settings and corresponding capacitance values.
2		
3		
4		
5	Continuous Current Scaling. Configures the drive to set the continuous current limit at a percentage of the drive peak current limit.	See Continuous Current Scaling Table below for switch settings and corresponding values.
6		
7		
8	Peak and Continuous Current Scaling. Adjusts both the peak and continuous drive current limits.	See Peak and Continuous Current Scaling Table below for switch settings and corresponding values.
9		
10		

*Continuous Current Scaling Table*

Default switch settings are shaded.

Switch	Continuous Current Scaling (% of Peak Current)							
	50	43.6	37.6	31.6	25.6	19.7	13.7	7.75
SW4-5	OFF	ON	OFF	ON	OFF	ON	OFF	ON
SW4-6	OFF	OFF	ON	ON	OFF	OFF	ON	ON
SW4-7	OFF	OFF	OFF	OFF	ON	ON	ON	ON

*Peak and Continuous Current Scaling Table*

Default switch settings are shaded.

Switch	Peak and Continuous Current Scaling* (A <sub>peak</sub> )							
	50	43.63	38.60	34.61	31.37	28.67	26.40	24.47
SW4-8	OFF	ON	OFF	ON	OFF	ON	OFF	ON
SW4-9	OFF	OFF	ON	ON	OFF	OFF	ON	ON
SW4-10	OFF	OFF	OFF	OFF	ON	ON	ON	ON

\*Note: By default, the continuous current limit will be half of the peak value. However, DIP Switches SW4-5, 6, and 7 can set the continuous limit to a lesser percentage of the peak value.

**Potentiometer Functions**

Potentiometer	Description	Turning CW
1	Loop gain adjustment for duty cycle / voltage / velocity modes. Turn this pot fully CCW in current mode.	Increases gain
2	Current limit. It adjusts both continuous and peak current limit while maintaining their ratio.	Increases limit
3	Reference gain. Adjusts the ratio between input signal and output variables (voltage, current, or velocity).	Increases gain
4	Offset / Test. Used to adjust any imbalance in the input signal or in the amplifier. Can also be used as an on-board signal source for testing purposes.	Adjusts offset in negative direction

Note: Potentiometers are approximately linear and have 12 active turns with 1 inactive turn on each end. Test points are provided on the drive PCB near each potentiometer to measure the potentiometer value.

**Loop Tuning Switch Functions**

In general, the drive will not need to be further tuned beyond the default configuration. However, for applications requiring more precise tuning, DIP switches can be used to adjust the current and velocity loop tuning values. Some general rules of thumb to follow when tuning the drive are:

- A larger resistor value will increase the proportional gain, and therefore create a faster response time.
- A larger capacitor value will increase the integration time, and therefore create a slower response time.

Proper tuning will require careful observation of the loop response on a digital oscilloscope to find optimal DIP switch settings for the specific application.

**(Note: Drive cover must be removed to access SW3 and SW4)**

SW3 DIP switches add additional resistance and capacitance to the current loop tuning circuitry. SW3 switches 1-5 add additional series resistance to the current loop gain resistor, and SW3 switches 6-10 add additional parallel capacitance to the current loop integrator capacitor. The resulting capacitance and resistance values are given in the tables below along with the appropriate DIP switch settings. The default switch settings are shaded in the SW3 tables below.

<b>SW3</b>																
<b>Switch</b>	<b>Current Loop Proportional Gain Resistance Options (kΩ)</b>															
	<b>10</b>	<b>26</b>	<b>42</b>	<b>58</b>	<b>74</b>	<b>91</b>	<b>107</b>	<b>123</b>	<b>135</b>	<b>151</b>	<b>167</b>	<b>183</b>	<b>199</b>	<b>216</b>	<b>232</b>	<b>248</b>
SW3-1	ON	OFF	ON	OFF	ON	OFF	ON	OFF	ON	OFF	ON	OFF	ON	OFF	ON	OFF
SW3-2	ON	ON	OFF	OFF	ON	ON	OFF	OFF	ON	ON	OFF	OFF	ON	ON	OFF	OFF
SW3-3	ON	ON	ON	ON	OFF	OFF	OFF	OFF	ON	ON	ON	ON	OFF	OFF	OFF	OFF
SW3-4	ON	ON	ON	ON	ON	ON	ON	ON	OFF	OFF	OFF	OFF	OFF	OFF	OFF	OFF
SW3-5	ON	ON	ON	ON	ON	ON	ON	ON	ON	ON	ON	ON	ON	ON	ON	ON
<b>Switch (continued)</b>	<b>260</b>	<b>276</b>	<b>292</b>	<b>308</b>	<b>324</b>	<b>341</b>	<b>357</b>	<b>373</b>	<b>385</b>	<b>401</b>	<b>417</b>	<b>433</b>	<b>449</b>	<b>466</b>	<b>482</b>	<b>498</b>
SW3-1	ON	OFF	ON	OFF	ON	OFF	ON	OFF	ON	OFF	ON	OFF	ON	OFF	ON	OFF
SW3-2	ON	ON	OFF	OFF	ON	ON	OFF	OFF	ON	ON	OFF	OFF	ON	ON	OFF	OFF
SW3-3	ON	ON	ON	ON	OFF	OFF	OFF	OFF	ON	ON	ON	ON	OFF	OFF	OFF	OFF
SW3-4	ON	ON	ON	ON	ON	ON	ON	ON	OFF	OFF	OFF	OFF	OFF	OFF	OFF	OFF
SW3-5	OFF	OFF	OFF	OFF	OFF	OFF	OFF	OFF	OFF	OFF	OFF	OFF	OFF	OFF	OFF	OFF

<b>SW3</b>																	
<b>Switch</b>	<b>Current Loop Integrator Capacitance Options (μF)</b>																
	<b>.0047</b>	<b>.0169</b>	<b>.0314</b>	<b>.0436</b>	<b>.0564</b>	<b>.0686</b>	<b>.0831</b>	<b>.0953</b>	<b>.1094</b>	<b>.1216</b>	<b>.1361</b>	<b>.1483</b>	<b>.1611</b>	<b>.1733</b>	<b>.1878</b>	<b>.2000</b>	<b>SHORT</b>
SW3-6	OFF	ON	OFF	ON	OFF	ON	OFF	ON	OFF	ON	OFF	ON	OFF	ON	OFF	ON	ON
SW3-7	OFF	OFF	ON	ON	OFF	OFF	ON	ON	OFF	OFF	ON	ON	OFF	OFF	ON	ON	ON
SW3-8	OFF	OFF	OFF	OFF	ON	ON	ON	ON	OFF	OFF	OFF	OFF	ON	ON	ON	ON	ON
SW3-9	OFF	OFF	OFF	OFF	OFF	OFF	OFF	OFF	ON	ON	ON	ON	ON	ON	ON	ON	ON
SW3-10	OFF	OFF	OFF	OFF	OFF	OFF	OFF	OFF	OFF	OFF	OFF	OFF	OFF	OFF	OFF	OFF	ON

SW4 DIP switches 1-4 add additional parallel capacitance to the velocity loop integrator capacitor. The resulting capacitance values are given in the table below along with the appropriate DIP switch settings. The default switch settings are shaded in the SW4 table below.

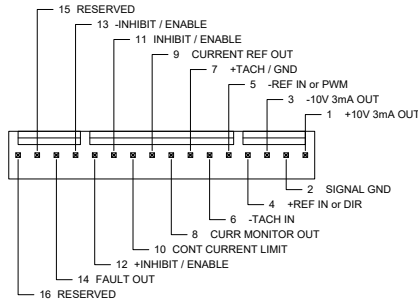
<b>SW4</b>																
<b>Switch</b>	<b>Velocity Loop Integrator Capacitance Options (μF)</b>															
	<b>0.047</b>	<b>0.147</b>	<b>0.294</b>	<b>0.421</b>	<b>0.544</b>	<b>0.671</b>	<b>0.791</b>	<b>0.918</b>	<b>1.047</b>	<b>1.194</b>	<b>1.341</b>	<b>1.468</b>	<b>1.591</b>	<b>1.718</b>	<b>1.838</b>	<b>1.965</b>
SW4-1	OFF	ON	OFF	ON	OFF	ON	OFF	ON	OFF	ON	OFF	ON	OFF	ON	OFF	ON
SW4-2	OFF	OFF	ON	ON	OFF	OFF	ON	ON	OFF	OFF	ON	ON	OFF	OFF	ON	ON
SW4-3	OFF	OFF	OFF	OFF	ON	ON	ON	ON	OFF	OFF	OFF	OFF	ON	ON	ON	ON
SW4-4	OFF	OFF	OFF	OFF	OFF	OFF	OFF	OFF	ON	ON	ON	ON	ON	ON	ON	ON

Note: The velocity loop integrator capacitor can be shorted entirely by setting SW1-4 to OFF.

**MECHANICAL INFORMATION**

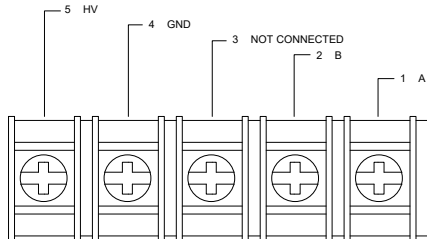
**P1 - Signal Connector**

Connector Information		16-pin, 2.54 mm spaced, friction lock header
Mating Connector	Details	Molex: P/N 22-01-3167 (connector) and P/N 08-50-0114 (insert terminals)
	Included with Drive	Yes



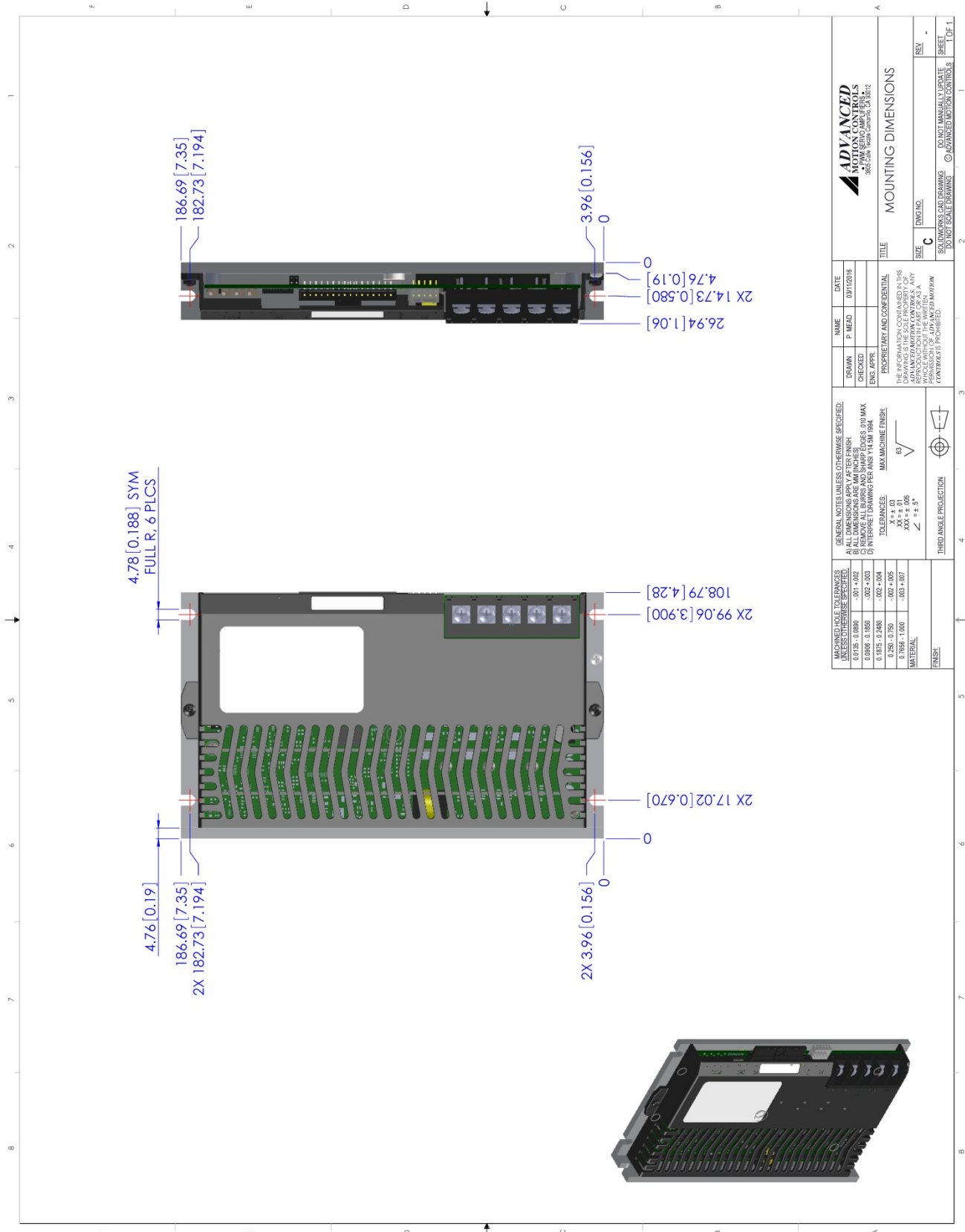
**P2 - Power Connector**

Connector Information		5-port, 11.10 mm spaced, screw terminal
Mating Connector	Details	N/A
	Included with Drive	N/A



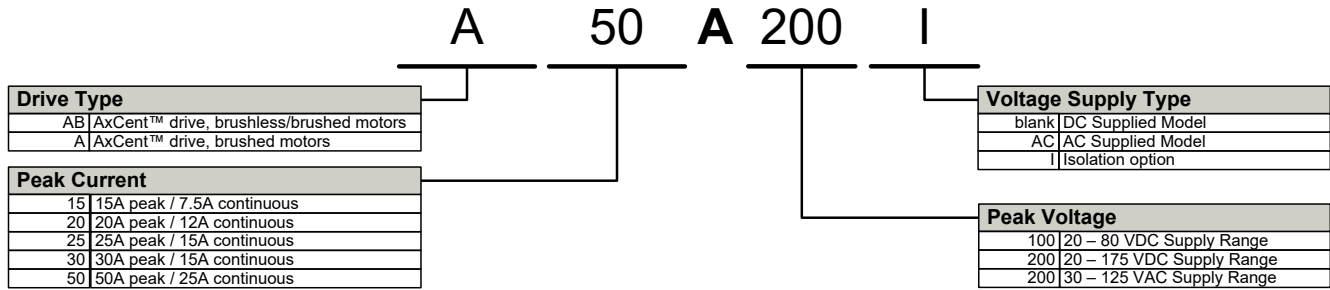


**MOUNTING DIMENSIONS**



<p><b>ADVANCED</b> MOTION CONTROLS 3805 Calle Tecate, Camarillo, CA 93012</p>		<p><b>MOUNTING DIMENSIONS</b></p>													
NAME	DATE	SIZE	REV.												
P. MEAD	03/11/2018	C	-												
DRAWN	DATE	SOLIDWORKS CAD DRAWING													
ENG. APPR.	PROPRIETARY AND CONFIDENTIAL	DO NOT MANUALLY UPDATE													
<p>THE INFORMATION CONTAINED IN THIS DRAWING IS THE SOLE PROPERTY OF ADVANCED MOTION CONTROLS. ANY REPRODUCTION IN PART OR AS A WHOLE WITHOUT THE WRITTEN PERMISSION OF ADVANCED MOTION CONTROLS IS PROHIBITED.</p>															
<p>GENERAL NOTES: UNLESS OTHERWISE SPECIFIED:          A) ALL DIMENSIONS APPLY AFTER FINISH.          B) DIMENSIONS ARE TO CENTER UNLESS OTHERWISE SPECIFIED.          C) REMOVE ALL BURRS AND SHARP EDGES 0.10 MAX.          D) INTERPRET DRAWING PER ANSI Y14.5M 1994.</p>		<p>THIRD ANGLE PROJECTION</p>													
<p>MACHINED HOLE TOLERANCES UNLESS OTHERWISE SPECIFIED:</p> <table border="1"> <tr> <td>0.015 - 0.050</td> <td>±0.01 - 0.02</td> </tr> <tr> <td>0.050 - 0.100</td> <td>±0.02 - 0.03</td> </tr> <tr> <td>0.100 - 0.250</td> <td>±0.03 - 0.04</td> </tr> <tr> <td>0.250 - 0.500</td> <td>±0.04 - 0.05</td> </tr> <tr> <td>0.500 - 1.000</td> <td>±0.05 - 0.06</td> </tr> <tr> <td>1.000 - 2.000</td> <td>±0.06 - 0.08</td> </tr> </table>		0.015 - 0.050	±0.01 - 0.02	0.050 - 0.100	±0.02 - 0.03	0.100 - 0.250	±0.03 - 0.04	0.250 - 0.500	±0.04 - 0.05	0.500 - 1.000	±0.05 - 0.06	1.000 - 2.000	±0.06 - 0.08	<p>FINISH</p>	
0.015 - 0.050	±0.01 - 0.02														
0.050 - 0.100	±0.02 - 0.03														
0.100 - 0.250	±0.03 - 0.04														
0.250 - 0.500	±0.04 - 0.05														
0.500 - 1.000	±0.05 - 0.06														
1.000 - 2.000	±0.06 - 0.08														
<p>TOLEANCES:          FRACTIONAL          XX ± 0.01          XX ± 0.05          XX ± 0.10          XX ± 0.15          XX ± 0.20</p>		<p>MAX MACHINE FINISH</p>													

**PART NUMBERING INFORMATION**



ADVANCED Motion Controls analog series of servo drives are available in many configurations. Note that not all possible part number combinations are offered as standard drives. All models listed in the selection tables of the website are readily available, standard product offerings.

ADVANCED Motion Controls also has the capability to promptly develop and deliver specified products for OEMs with volume requests. Our Applications and Engineering Departments will work closely with your design team through all stages of development in order to provide the best servo drive solution for your system. Equipped with on-site manufacturing for quick-turn customs capabilities, ADVANCED Motion Controls utilizes our years of engineering and manufacturing expertise to decrease your costs and time-to-market while increasing system quality and reliability.

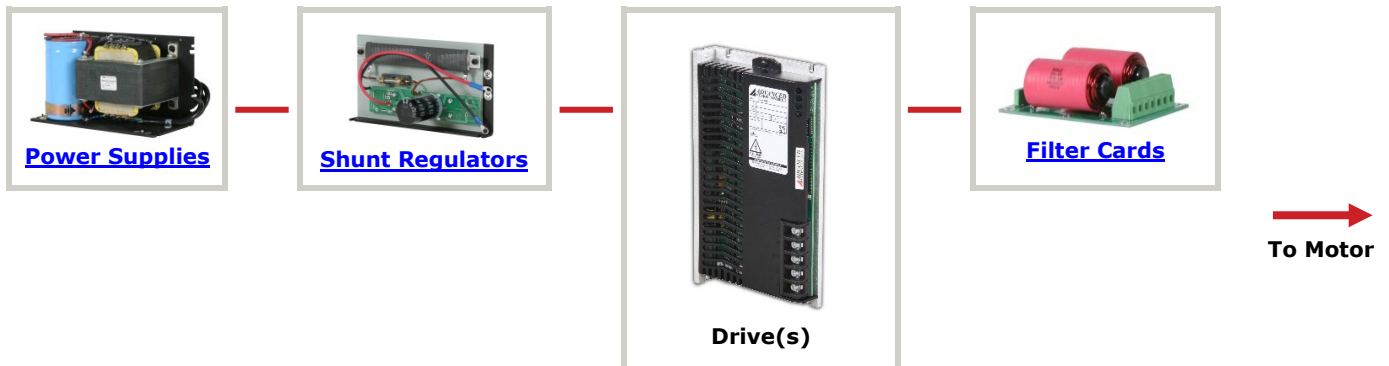
**Examples of Modifications and Customized Products**

- ▲ Integration of Drive into Motor Housing
  - ▲ Mount OEM PCB onto Drive Without Cables
  - ▲ Multi-axis Configuration for Compact System
  - ▲ Custom PCB and Baseplate for Optimized Footprint
  - ▲ RTV/Epoxy Components for High Vibration
  - ▲ OEM Specified Connectors for Instant Compatibility
  - ▲ OEM Specified Silkscreen for Custom Appearance
  - ▲ Increased Thermal Limits for High Temp. Operation
- ▲ Integrate OEM Circuitry onto Drive PCB
  - ▲ Custom Control Loop Tuned to Motor Characteristics
  - ▲ Custom I/O Interface for System Compatibility
  - ▲ Preset Switches and Pots to Reduce User Setup
  - ▲ Optimized Switching Frequency
  - ▲ Ramped Velocity Command for Smooth Acceleration
  - ▲ Remove Unused Features to Reduce OEM Cost
  - ▲ Application Specific Current and Voltage Limits

Feel free to contact Applications Engineering for further information and details.

**Available Accessories**

ADVANCED Motion Controls offers a variety of accessories designed to facilitate drive integration into a servo system. Visit [www.a-m-c.com](http://www.a-m-c.com) to see which accessories will assist with your application design and implementation.



All specifications in this document are subject to change without written notice. Actual product may differ from pictures provided in this document.